Application Serial No.: 09/926,541

Reply to Office Action dated April 15, 2003

AMENDMENTS TO THE CLAIMS

This listing of the claims will replace all prior versions, and listing, of claims in the application:

Listing of Claims:

- 1-14. (Canceled)
- 15. (Currently Amended) The robot according to claim 14 27, wherein the opening is configured to be formed by a pipe socket fixedly mounted on the manipulator.
- 16. (Currently Amended) The robot according to claim 14 27, wherein the at least two holders include holder includes a fastening means in the form of a curved collar.
- 17. (Currently Amended) The robot according to claim 16, wherein the at least two holders are holder is configured to be fixed by snap action with the curved collar.
- 18. (Currently Amended) The robot according to claim 16, wherein the at least two holders are holder is configured to be fixed with a hose clamp.
 - 19. (Canceled)
- 20. (Currently Amended) The robot according to claim 19 27, wherein:
 the at least two holders holder and the at least two lids lid have compatible shapes,
 and

the at least two holders holder and the at least two lids lid cover at least part of the at least one opening when mounted together.

21. (Currently Amended) The robot according to claim 19 27, wherein the at least two holders holder and the at least two lids lid are configured to cover the opening and to form a tight seal of the opening.



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22. (Canceled)

23. (Currently Amended) The robot according to claim 14 27, the at least two lids

are <u>lid is</u> configured to be divided into sections through at least one direction.

24. (Canceled)

25. (Currently Amended) The process according to claim 24 28, wherein at least two

lids are at least one of the removable sections of lid is configured to be compatible with the at

least two holders holder, and wherein the at least two holders holder and the at least two lids

lid are fixed in the opening to cover at least part of the at least one opening.

26. (Currently Amended) The process according to claim 25, wherein the at least

two holders holder and the at least two lids lid are configured to cover the at least one

opening tight-fittingly when mounted together.

27. (New) An industrial robot comprising:

a control system including at least one cable set; and

a manipulator having an opening and a holder provided within said opening, said

holder being detachably fixed along a section of an edge of said opening, said at least one

cable set extending through said holder provided within said opening,

wherein said manipulator includes a lid configured to be detachably fixed to said

edge, said lid having removable sections.

28. (New) A process for fastening in an industrial robot, the robot including a control

system having at least one cable set, and a manipulator having an opening and a holder

provided within the opening, the at least one cable set extending through the holder, said

process comprising the steps of:

detachably fixing the holder along a section of an edge of the opening; and

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detachably fixing a lid to the edge, wherein the lid has removable sections.

29. (New) An industrial robot comprising:

a control system including at least one cable set; and

a manipulator having an opening and a holder provided within said opening, said holder having a collar with a U-shaped cross section that detachably connects to a section of an edge of said opening, said at least one cable set extending through said holder provided within said opening.

- 30. (New) The robot according to claim 29, wherein the opening is configured to be formed by a pipe socket fixedly mounted on the manipulator.
- 31. (New) The robot according to claim 29, wherein the holder is configured to be fixed with a hose clamp.
- 32. (New) The robot according to claim 29, wherein said manipulator includes a lid configured to be detachably fixed to said edge.
 - 33. (New) The robot according to claim 32, wherein said lid has removable sections.
 - 34. (New) The robot according to claim 32, wherein:

said holder and said lid have compatible shapes, and

said holder and said lid cover at least part of said opening when mounted together.

35. (New) The robot according to claim 32, wherein said holder and said lid are configured to cover said opening and to form a tight seal of said opening.

